

# Advanced Active Robotic TKA ; A learning curve of surgical time and alignment accuracy

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## **Yong-Beom Park**

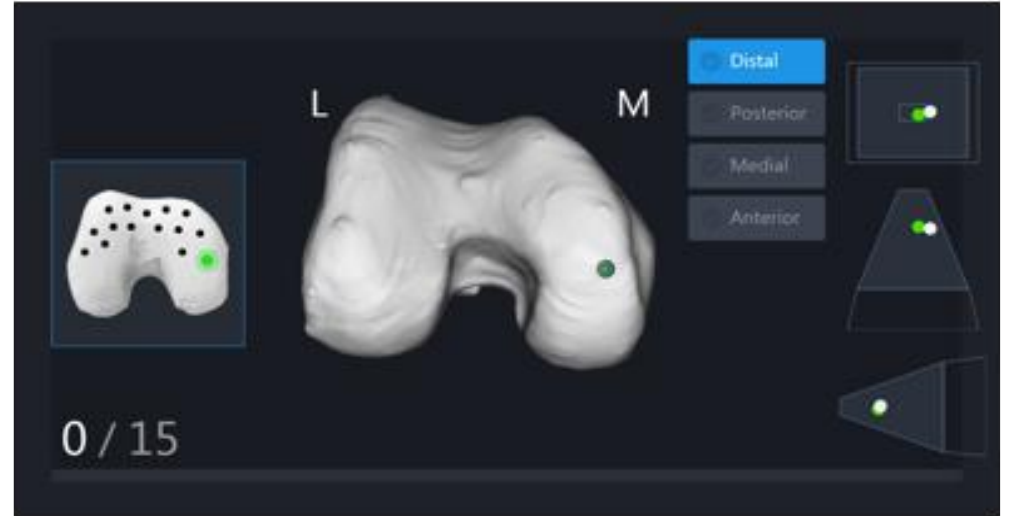
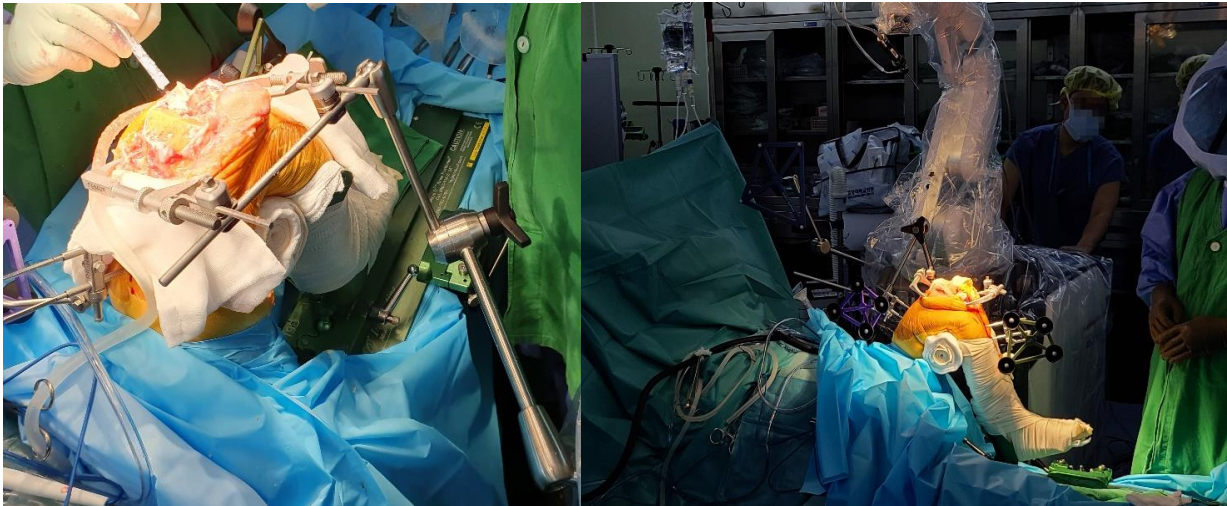
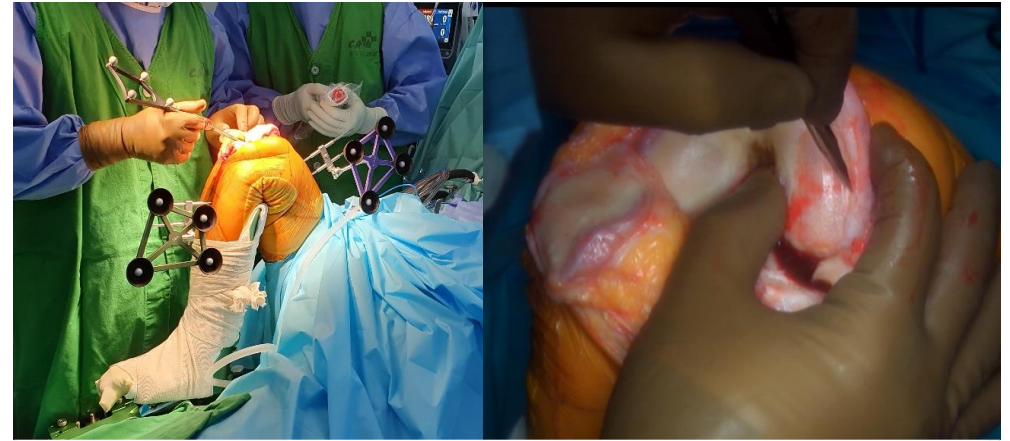
**Consultant, Robot for Knee Arthroplasty, Curexo Inc.**

**Consultant, Cartilage Regeneration using ADSVF, Rokat Health Care Inc.**

# Several Robotics for TKA



# New technology: Learning Curve





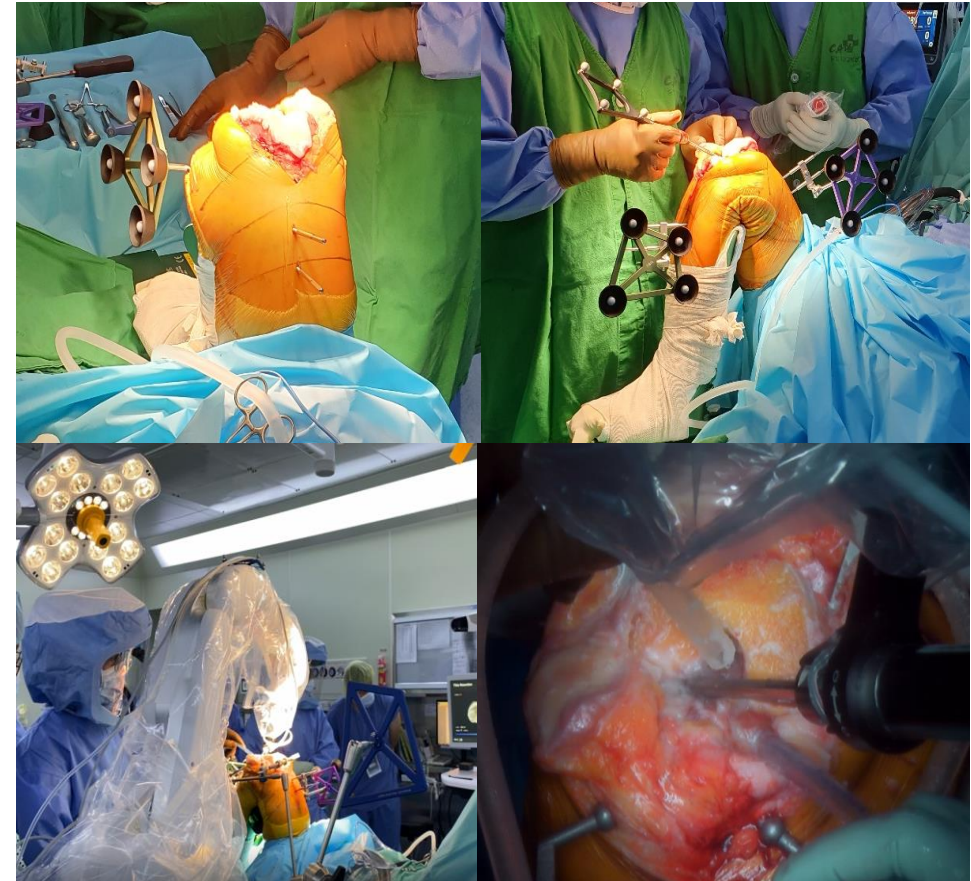
# Purpose

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- to determine the learning curve necessary to minimize the **operative time** and to evaluate the **alignment accuracy** when using advanced active robotic TKA

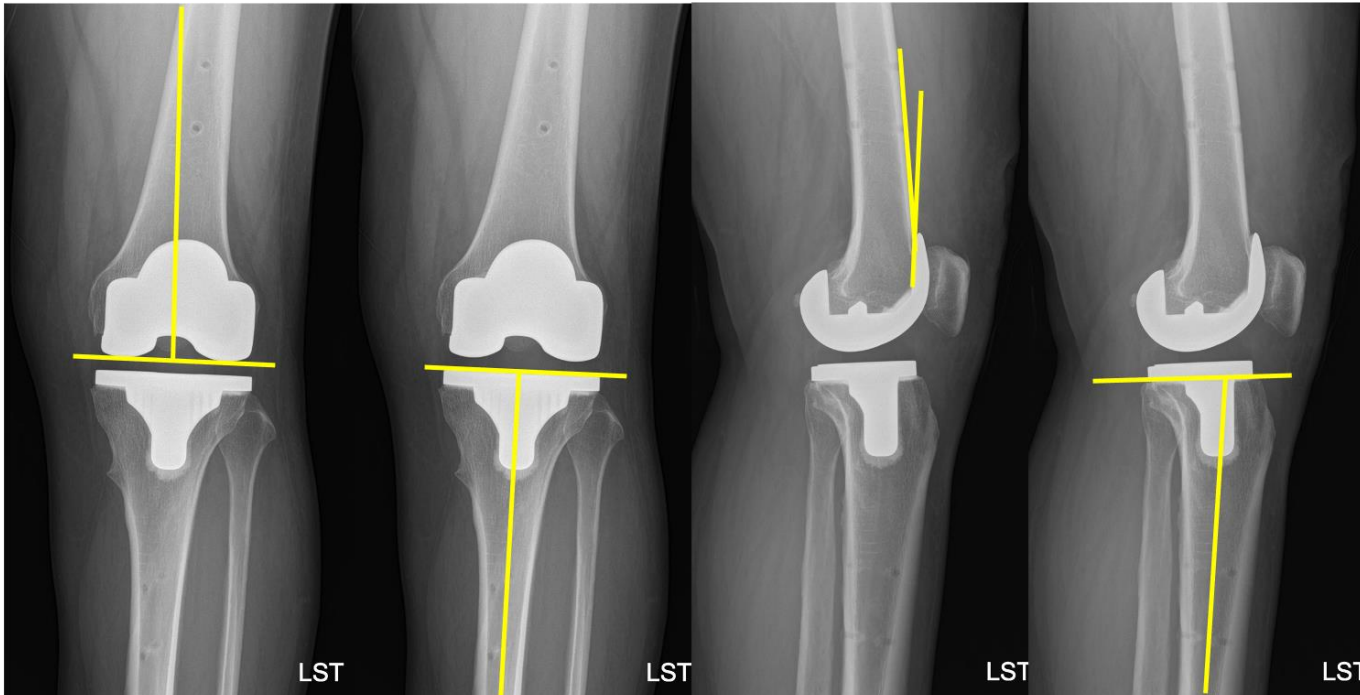
# Methods: Robotic Surgery

- TKA using newly advanced active robotic system
  - ✓ Robot (CUVIS-Joint<sup>®</sup>; CUREXO Inc.)
  - ✓ Image(CT)-base, active



# Methods: Patients & Outcome variables

- 60 consecutive primary TKAs
  - ✓ Age: 73.4 years, Sex: 54/6 (F/M), BMI: 27.1 kg/m<sup>2</sup>
  - ✓ Preoperative HKA angle: varus 7.7°
- Operation time: tourniquet (incision to closure)
- Radiological evaluation
  - ✓ Alignment lower leg and component



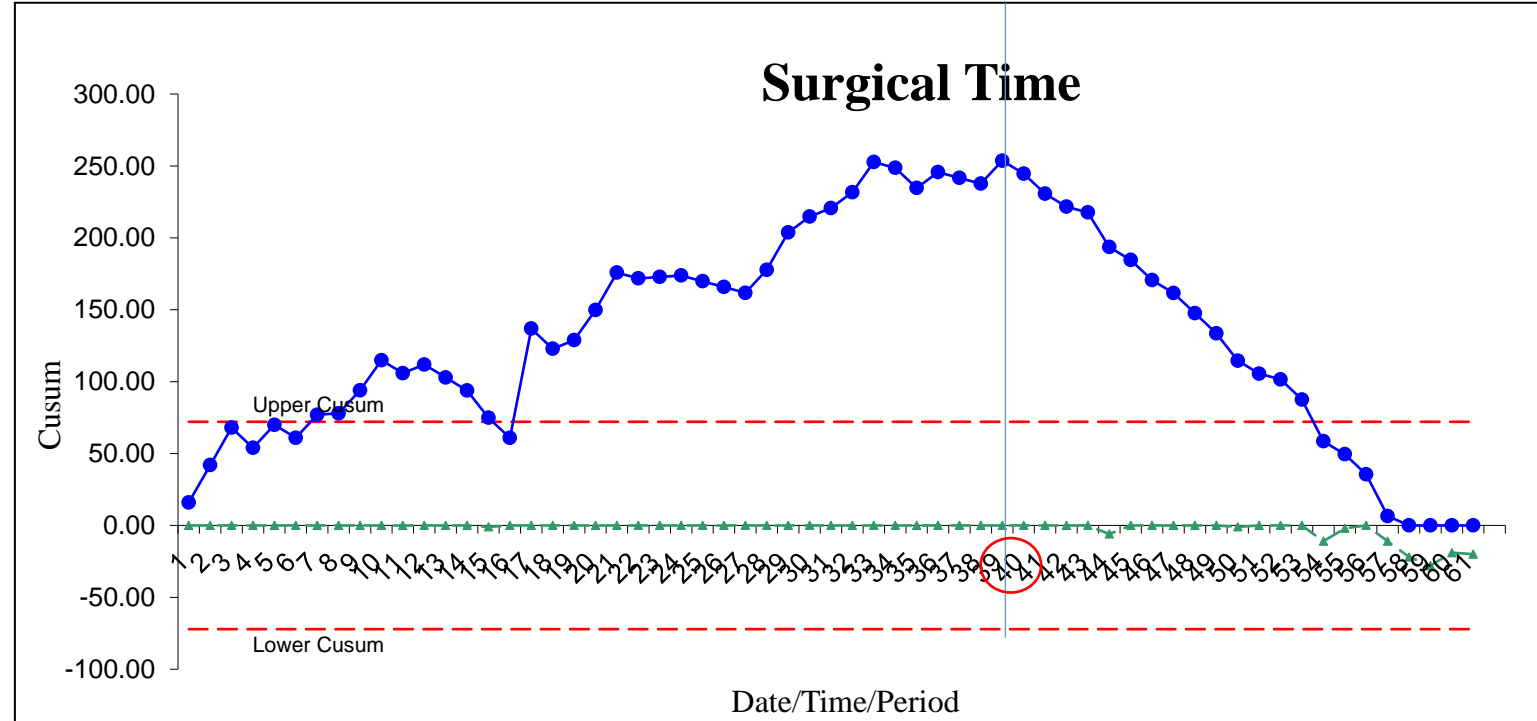
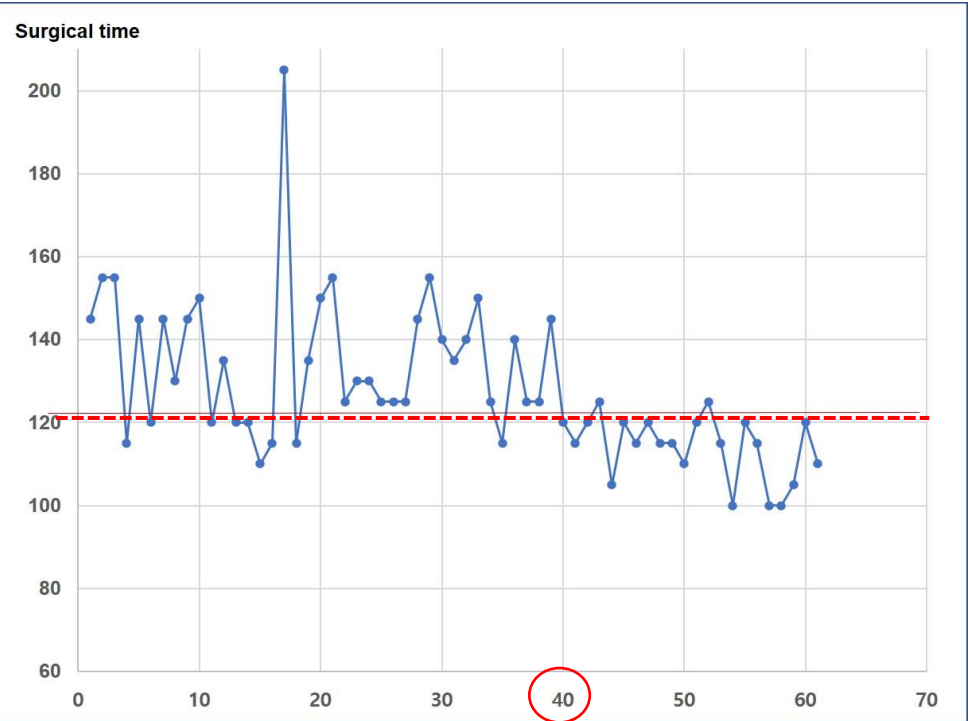
# Methods: Statistical Analysis

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- **Group classification**
  - ✓ 60 cases of robotic TKAs
  - ✓ 6 groups according to the order of surgery (10 patients per group)
  - Kruskal-Wallis test & post-hoc comparison
  
- **Cumulative summation analysis (CUSUM)**

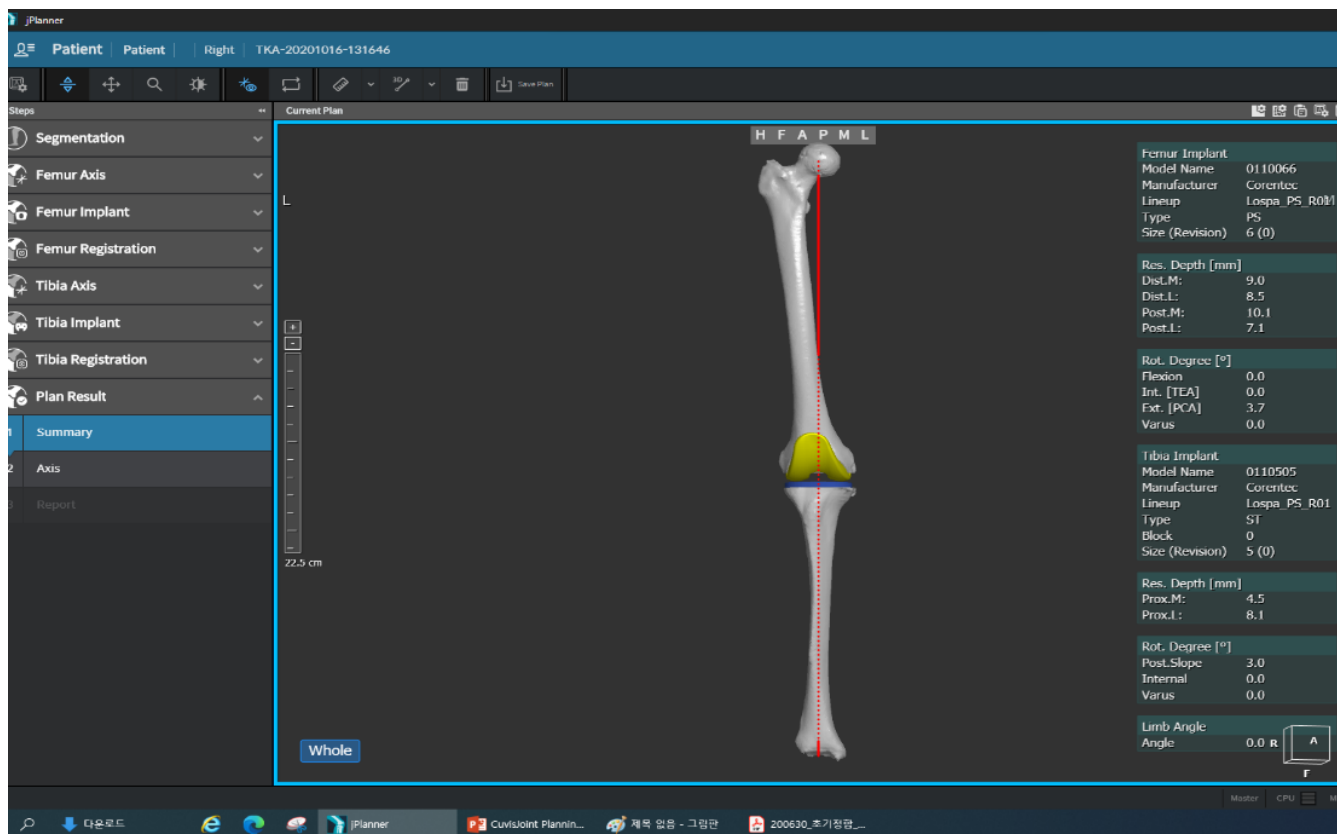


# Results: Operation Time



|                | Group1     | Group2     | Group3     | Group4     | Group5     | Group6     |                  |
|----------------|------------|------------|------------|------------|------------|------------|------------------|
| <b>OP time</b> | <b>138</b> | <b>130</b> | <b>133</b> | <b>130</b> | <b>116</b> | <b>111</b> | <b>&lt;0.001</b> |

# Results: Lower Limb Alignment



|           | Criteria                | Robot (n=60) |
|-----------|-------------------------|--------------|
| HKA angle | $180^\circ \pm 3^\circ$ | 57 (95.0%)   |

|          | HKA angle |
|----------|-----------|
| Preop    | 7.7 varus |
| Planning | 0         |
| Postop   | 1.6 varus |

|           | Group1 | Group2 | Group3 | Group4 | Group5 | Group6 |       |
|-----------|--------|--------|--------|--------|--------|--------|-------|
| HKA angle | 1.9    | 1.5    | 1.7    | 1.5    | 1.6    | 1.4    | 0.126 |

# Results: Component Alignment

|          | Criteria               | Proportion(n=60) | angle        |
|----------|------------------------|------------------|--------------|
| $\alpha$ | $90^\circ \pm 3^\circ$ | 59 (98.3%)       | $89.1^\circ$ |
| $\beta$  | $90^\circ \pm 3^\circ$ | 58 (96.7%)       | $89.3^\circ$ |
| $\Gamma$ | $0^\circ \pm 5^\circ$  | 56(93.3%)        | $2.8^\circ$  |
| $\delta$ | $87^\circ \pm 3^\circ$ | 55(91.7%)        | $85.6^\circ$ |

|          | Group1 | Group2 | Group3 | Group4 | Group5 | Group6 |       |
|----------|--------|--------|--------|--------|--------|--------|-------|
| $\alpha$ | 89.1   | 89.3   | 89.0   | 89.2   | 89.1   | 89.0   | 0.845 |
| $\beta$  | 89.4   | 89.1   | 89.3   | 89.3   | 89.2   | 89.5   | 0.548 |
| $\gamma$ | 3.0    | 2.7    | 2.9    | 2.8    | 2.7    | 2.7    | 0.779 |
| $\delta$ | 85.5   | 86.1   | 85.3   | 85.6   | 85.4   | 85.7   | 0.128 |

- **Robotic TKA with advanced active robotics**
  - ✓ **Operative time: 40 cases for learning curve**
  - ✓ **Accuracy: no learning curve**
    - **Favorable accuracy**
      - :Lower limb alignment**
      - :Component alignment, especially coronal plane**



# References

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