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# The Influence of Different Rotator Cuff Tears In Relation to Glenoid Depth on Glenohumeral Stability – A Robotic Biomechanical Analysis

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- No conflicts of interest
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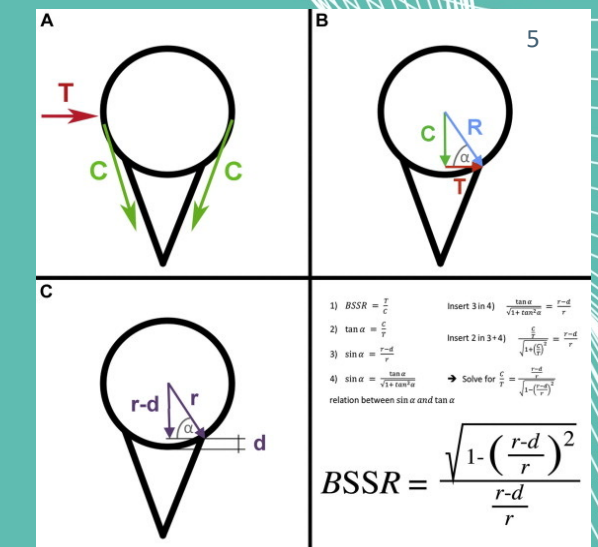
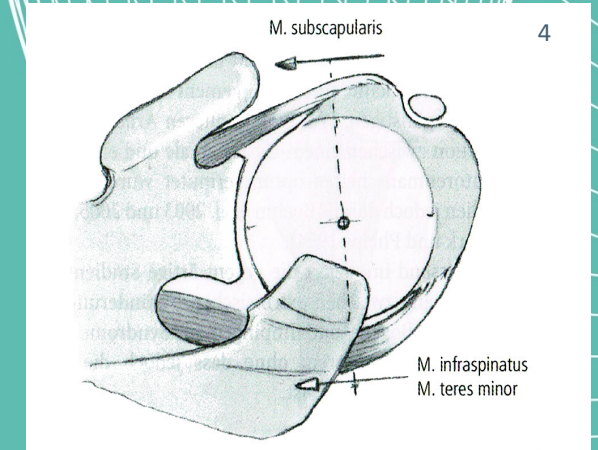
# Background – Influence of rotator cuff and concavity on joint stability

## Active partner - Rotator cuff

- Crucial role of „the force couples“ <sup>1</sup>
- Preservation of the coronary and transverse couple essential <sup>2</sup>
- Outstanding role for M. subscapularis (SSC) <sup>3</sup>

## Passive partner - Glenoid concavity

- Bone loss alone is not sufficient to represent biomechanical situation <sup>5,6</sup>
- Bony shoulder stability ratio (BSSR) as a calculation method <sup>5</sup>
- Confirmation of the theory and the finite model by biomechanical studies of our group <sup>6</sup>





# Introduction

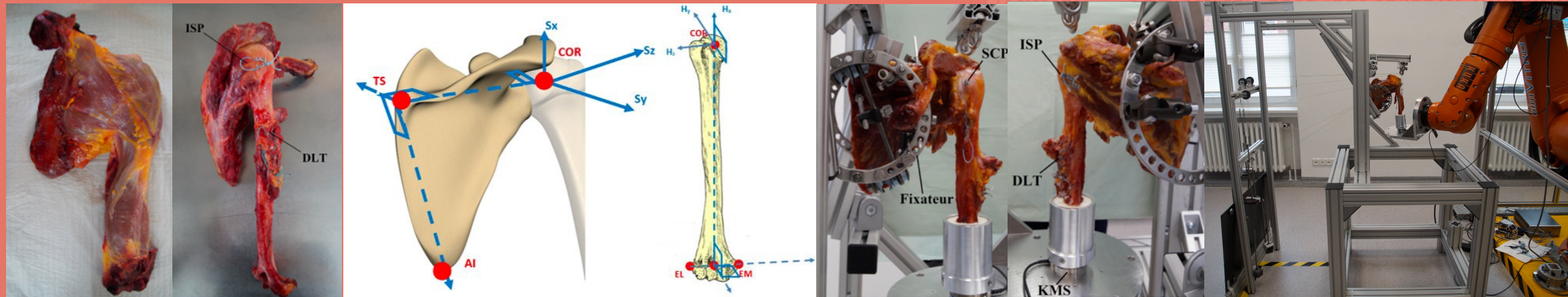
- Aim of this study
  - Investigation of the Influence of different Rotator Cuff Tears (RCTs) in relation to glenoid depth on glenohumeral stability (GHS) by robotic biomechanical analysis
- Hypotheses
  - M.subscapularis (SSC) rupture has a greater impact on the GHS than other ruptures of single tendons
  - A distinctive glenoid depth or high BSSR increases the GHS





# Material and methods

- 8 human cadaver shoulders included ( $\bar{\varnothing}$  Age  $82,25 \pm 8,12$  (76-98) years)
  - Dissection of the rotator cuff and the long biceps tendon
- Coordinate system based on marked anatomical landmarks + CT
- Fixation of the scapula as well as the humerus in rail construct
- Movement and measurement of forces with industrial robot, robot-specific software and force-torque sensor





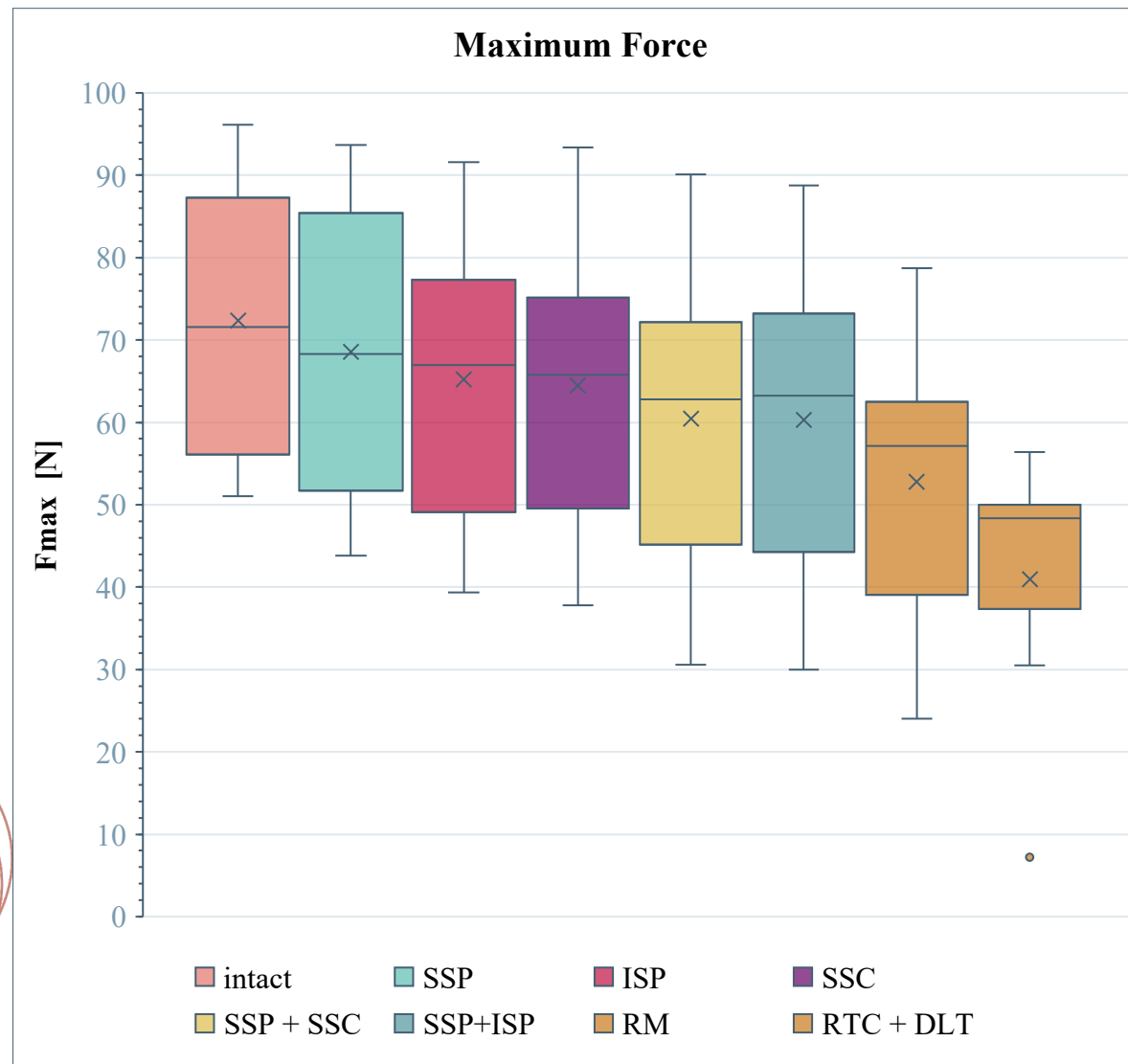
# Test Execution

- Loading of the reinforced tendons according to their cross-sectional area <sup>7,8</sup>
  - 8 optional configurations (SSP, SCP, ISP/TM, DLT)
- Glenohumeral abduction of 60°
- Starting position by centering the humeral head
- Subsequently Start Load & Shift sequence
- Analysis of
  - Maximum force ( $F_{max}$ ) in N
  - Maximum force increase ( $dF_{max}$ ) in N/mm
  - Glenoid depth in mm





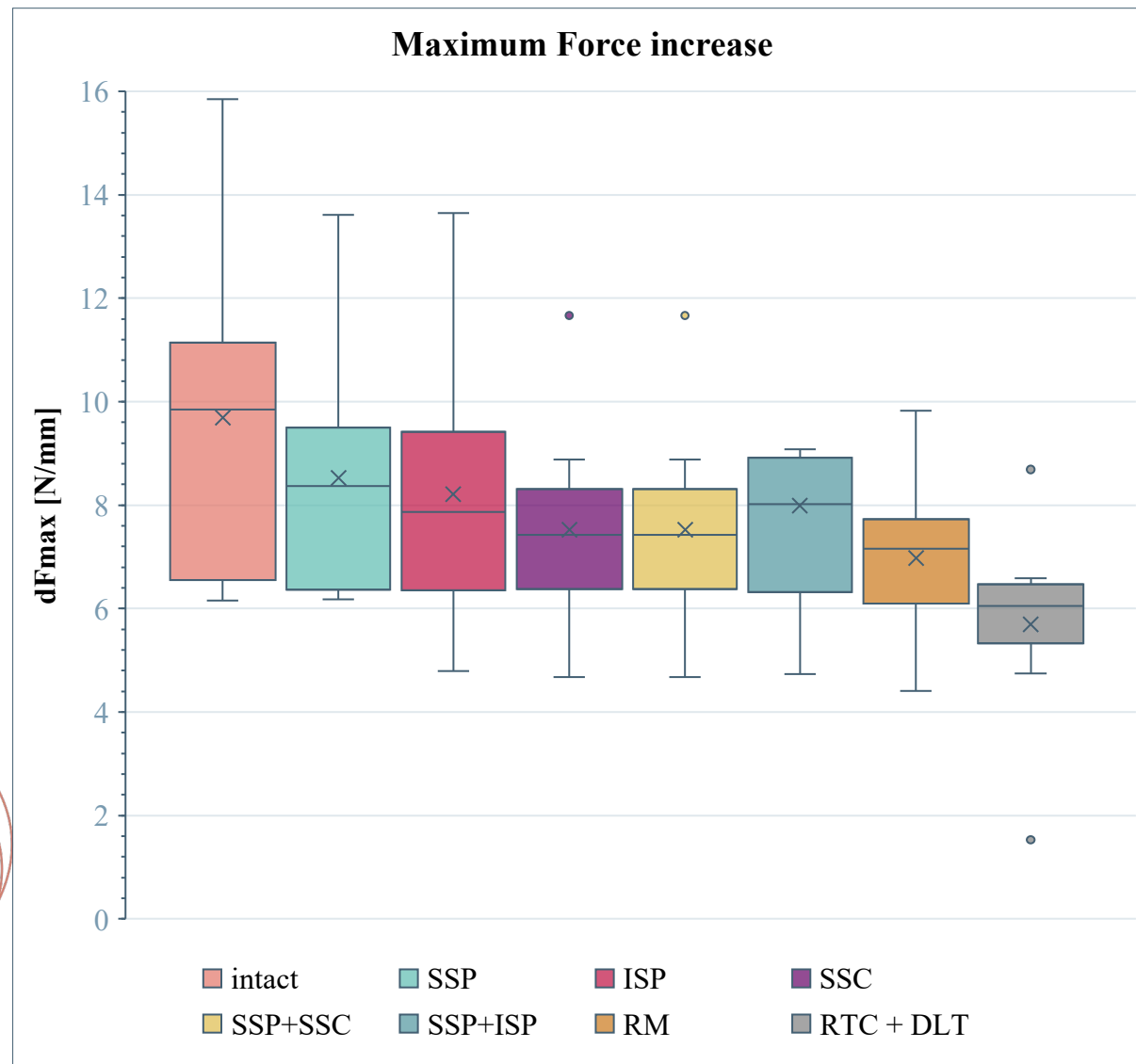
# Results – Force maximum



- $p < 0,001$  to intact RTC + DLT
- Single tendon ruptures
  - $\Delta F_{max}$  SSC 7,9 N
  - $\Delta F_{max}$  ISP/TM 7,2 N
  - $\Delta F_{max}$  SSP 3,8 N
- Combined ruptures
  - $\Delta F_{max}$  SSP + ISP/TM 12,1 N
  - $\Delta F_{max}$  SSP + SSC 11,9 N
- Mass rupture
  - $\Delta F_{max}$  SSP + SSC + ISP/TM 19,6 N



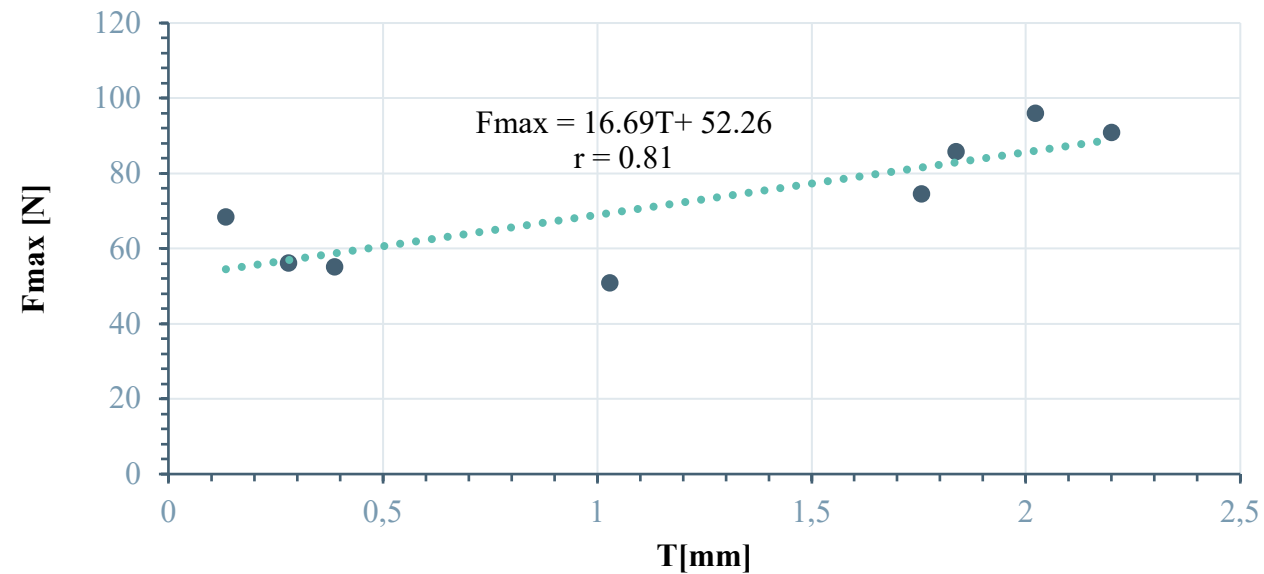
# Results – Maximum force increase



- $p < 0,05$  to intact RTC + DLT
- Single tendon ruptures
  - $\Delta dF_{max}$  SSC 1,5 N/mm
  - $\Delta dF_{max}$  ISP/TM 1,5 N/mm
  - $\Delta dF_{max}$  SSP 1,2 N/mm
- Combination ruptures
  - $\Delta dF_{max}$  SSP + ISP/TM 1,7 N/mm
  - $\Delta dF_{max}$  SSP + SSC 2,2 N/mm
- Mass rupture
  - $\Delta dF_{max}$  SSP + SSC + ISP/TM 2,7 N/mm

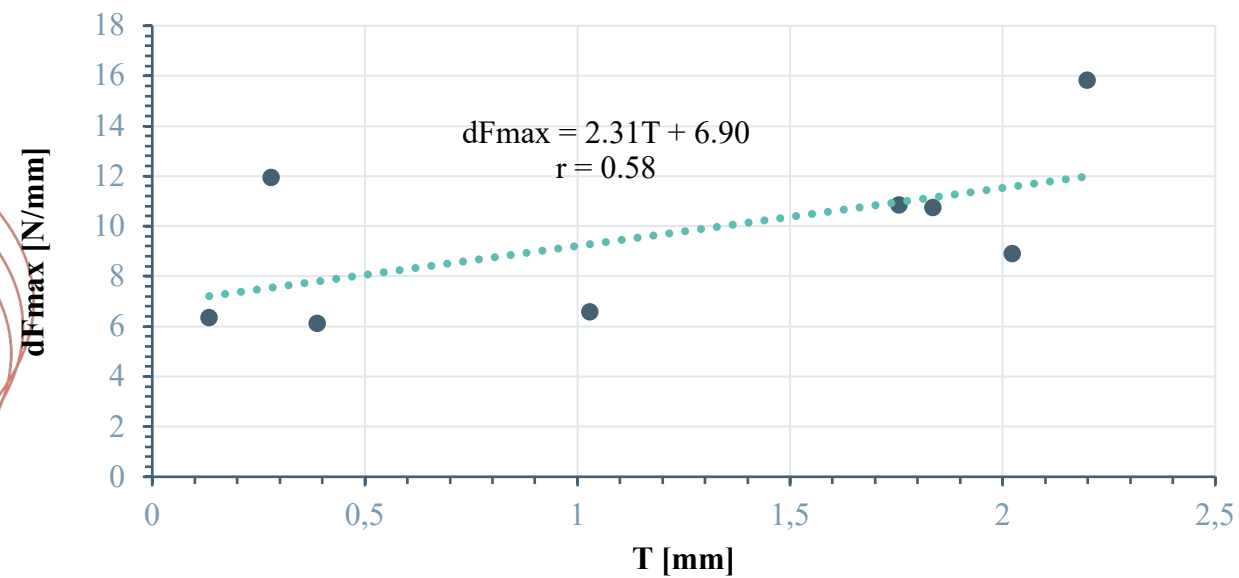


# Results – Correlation with glenoid depth



- Linear regression between glenoid depth and maximum force

→  $r = 0,81$



- Linear regression between glenoid depth and maximum force increase

→  $r = 0,58$



# Limitations

- Simplified model
  - Absence of muscle loading does not simulate rupture (but atony)
  - Soft tissues remain as passive stabilizer
- Physiological pull depends on training condition
- Relatively small number of specimens

